

Effects of Adhesive and Interphase Characteristics between Matrix and Reinforced Nanoparticle of AA8090/AlN Nanocomposites

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ABSTRACT— Interfaces play an essential role in virtually all composite materials. While composite materials are lessening in strength and stiffness properties, the interface begins to dominate their interesting properties. In this article two types of RVE models have been implemented using finite element analysis. Aluminum nitride nanoparticles were used as a reinforcing material in the matrix of AA8090 aluminum alloy. It has been observed that the nanoparticle did not overload during the transfer of load from the matrix to the nanoparticle via the interphase due to interphase between the nanoparticle and the matrix. The tensile strength and elastic modulus has increased with an interphase around aluminum nitride nanoparticles in the AA8090/AlN nanocomposites.

Keywords— RVE models, AlN, AA8090, finite element analysis, interphase

1. INTRODUCTION

Metal matrix composites (MMCs) have been drawn attention in recent years owing to the need for materials with high strength and stiffness in the field for a large number of functional and structural applications. The higher stiffness of ceramic particles can lead to an incremental increase in the stiffness of a composite [1, 2]. One of the major challenges when processing nanocomposites is achieving a homogeneous distribution of reinforcement in the matrix as it has a strong impact on the properties and the quality of the material. The current processing methods often generate agglomerated particles in the ductile matrix and as a result they exhibit extremely low ductility [3]. Particle clusters act as crack or decohesion nucleation sites at stresses lower than the matrix yield strength, causing the nanocomposite to fail at unpredictable low stress levels. Possible reasons resulting in particle clustering are chemical binding, surface energy reduction or particle segregation [4, 5, 6]. While manufacturing Al alloy-AlN nanocomposites, the wettability factor is the main concern irrespective of the manufacturing method. Its high surface activity restricts its incorporation in the metal matrix. One of the methods is to add surfactant which acts as a wetting agent in molten metal to enhance wettability of particulates. Researchers have successfully used several surfactants like Li, Mg, Ca, Zr, Ti, Cu, and Si for the synthesis of nanocomposites [7, 8, 9].

The objective of this article was to develop AA8090/AlN nanocomposites with and without wetting criteria of AlN by AA8090 molten metal. The RVE models were used to analyze the nanocomposites using finite Element analysis..

2. THEORETICAL BACKGROUND

Analyzing structures on a microstructural level, however, is clearly an inflexible problem. Analysis methods have therefore sought to approximate composite structural mechanics by analyzing a representative section of the composite microstructure, commonly called a Representative Volume Element (RVE). One of the first formal definitions of the RVE was given by Hill [10] who stated that the RVE was (1) structurally entirely typical of the composite material on average and (2) contained a sufficient number of inclusions such that the apparent moduli were independent of the RVE boundary displacements or tractions. Under axisymmetric as well as antisymmetric loading, a 2-D axisymmetric model can be applied for the cylindrical RVE, which can significantly reduce the computational work[11].

To derive the formulae for deriving the equivalent material constants, a homogenized elasticity model of the square representative volume element (RVE) as shown in figure 1 is considered. The dimensions of the three-dimensional RVE are $2a \times 2a \times 2a$. The cross-sectional area of the RVE is $2a \times 2a$. The elasticity model is filled with a single, transversely isotropic material that has five independent material constants (elastic moduli E_y and E_z , Poisson's ratios ν_{xy} , ν_{yz} and shear modulus G_{yz}). The general strain-stress relations relating the normal stresses and the normal strains are given below:

$$\varepsilon_x = \frac{\sigma_x}{E_x} - \frac{\nu_{xy}\sigma_y}{E_y} - \frac{\nu_{xz}\sigma_z}{E_z} \quad (1)$$

$$\varepsilon_y = -\frac{\nu_{yx}\sigma_x}{E_y} + \frac{\sigma_y}{E_y} - \frac{\nu_{yz}\sigma_z}{E_z} \quad (2)$$

$$\epsilon_z = -\frac{v_{zx}\sigma_x}{E_x} - \frac{v_{zy}\sigma_y}{E_y} + \frac{\sigma_z}{E_z} \quad (3)$$

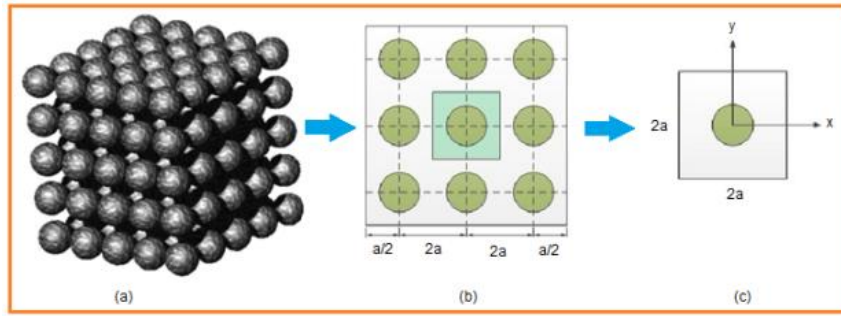


Figure 1: A square RVE containing a nanoparticle.

Let assume that $\sigma_{xy} = \sigma_{yx}$, $\sigma_{yz} = \sigma_{zy}$ and $\sigma_{zx} = \sigma_{xz}$. For plane strain conditions, $\epsilon_z = 0$, $\epsilon_{yz} = \epsilon_{zx} = 0$ and $v_{yz} = v_{zx}$. The above equations are rewritten as follows:

$$\epsilon_x = \frac{\sigma_x}{E_x} - \frac{v_{xy}\sigma_y}{E_y} - \frac{v_{yz}\sigma_z}{E_z} \quad (4)$$

$$\epsilon_y = -\frac{v_{xy}\sigma_x}{E_y} + \frac{\sigma_y}{E_y} - \frac{v_{yz}\sigma_z}{E_z} \quad (5)$$

$$\epsilon_z = -\frac{v_{yz}\sigma_x}{E_z} - \frac{v_{yz}\sigma_y}{E_z} + \frac{\sigma_z}{E_z} \quad (6)$$

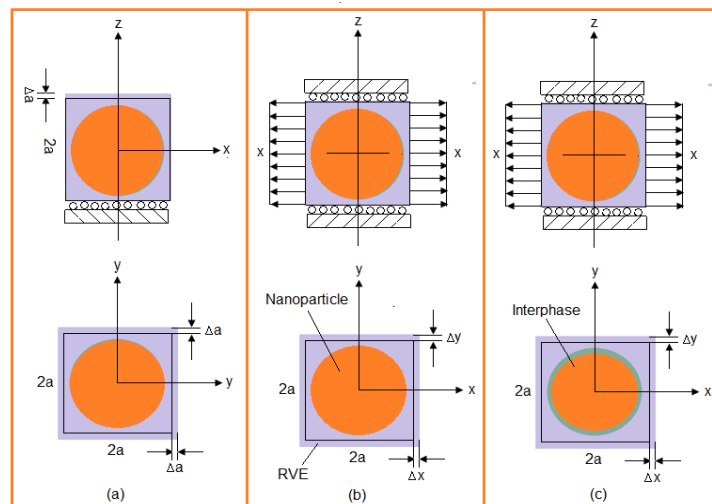


Figure 2: RVE models

To determine E_y and E_z , v_{xy} and v_{yz} , four equations are required. Two loading cases as shown in figure 2 have been designed to give four such equations based on the theory of elasticity. For load case (figure 2a), the stress and strain components on the lateral surface are:

$$\begin{aligned} \sigma_x &= \sigma_y = 0 \\ \epsilon_x &= \frac{\Delta a}{a} \text{ along } x = \pm a \text{ and } \epsilon_y = \frac{\Delta a}{a} \text{ along } y = \pm a \\ \epsilon_z &= \frac{\Delta a}{a} \end{aligned}$$

where Δa is the change of dimension a of cross-section under the stretch Δa in the z -direction. Integrating and averaging Eq. (6) on the plane $z = a$, the following equation can be arrived:

$$E_z = \frac{\sigma_{ave}}{\epsilon_z} = \frac{a}{\Delta a} \sigma_{ave} \quad (7)$$

where the average value of σ_z is given by:

$$\sigma_{ave} = \iint \sigma_z(x, y, a) dx dy \quad (8)$$

The value of σ_{ave} is evaluated for the RVE using finite element analysis (FEA) results.

Using Eq. (5) and the result (7), the strain along $y = \pm a$:

$$\varepsilon_y = -\frac{v_{yz}\sigma_z}{E_z} = -v_{yz}\frac{\Delta a}{a} = \frac{\Delta a}{a}$$

Hence, the expression for the Poisson's ratio v_{yz} is as follows:

$$v_{yz} = -1 \tag{9}$$

For load case (figure 2b), the square representative volume element (RVE) is loaded with a uniformly distributed load (negative pressure), P in a lateral direction, for instance, the x -direction. The RVE is constrained in the z -direction so that the plane strain condition is sustained to simulate the interactions of RVE with surrounding materials in the z -direction. Since $\varepsilon_z = 0$, $\sigma_z = v_{yz}(\sigma_x + \sigma_y)$ for the plain stress, the strain-stress relations can be reduced as follows:

$$\varepsilon_x = \left(\frac{1}{E_x} - \frac{1}{E_z}\right)\sigma_x - \left(\frac{v_{xy}}{E_y} + \frac{1}{E_z}\right)\sigma_y \tag{10}$$

$$\varepsilon_y = -\left(\frac{v_{xy}}{E_x} + \frac{1}{E_z}\right)\sigma_x + \left(\frac{1}{E_x} - \frac{1}{E_z}\right)\sigma_y \tag{11}$$

For the elasticity model as shown in figure 2b, one can have the following results for the normal stress and strain components at a point on the lateral surface:

$$\sigma_y = 0, \sigma_x = P$$

$$\varepsilon_x = \frac{\Delta x}{a} \text{ along } x = \pm a \text{ and } \varepsilon_y = \frac{\Delta y}{a} \text{ along } y = \pm a$$

where $\Delta x (>0)$ and $\Delta y (<0)$ are the changes of dimensions in the x - and y - direction, respectively for the load case shown in figure 2b. Applying Eq. (11) for points along $y = \pm a$ and Eq. (10) for points along $x = \pm a$, we get the following:

$$\varepsilon_y = -\left(\frac{v_{xy}}{E_x} + \frac{1}{E_z}\right)P = \frac{\Delta y}{a} \tag{12}$$

$$\varepsilon_x = \left(\frac{1}{E_x} - \frac{1}{E_z}\right)P = \frac{\Delta x}{a} \tag{13}$$

By solving Eqs. (12) and (13), the effective elastic modulus and Poisson's ratio in the transverse direction (xy -plane) as follows:

$$E_x = E_y = \frac{1}{\frac{\Delta x}{Pa} + \frac{1}{E_z}} \tag{14}$$

$$v_{xy} = \left(\frac{\Delta y}{Pa} + \frac{1}{E_z}\right) / \left(\frac{\Delta x}{Pa} + \frac{1}{E_z}\right) \tag{15}$$

In which E_z can be determined from Eq. (7). Once the change in lengths along x - and y - direction (Δx and Δy) are determined for the square RVE from the FEA, $E_y (= E_x)$ and v_{xy} can be determined from Eqs. (14) and (15), correspondingly.

The young's modulus of the interphase is obtained by the following formula:

$$E_i(r) = (\alpha E_p - E_m) \left(\frac{r_i - r}{r_i - r_p}\right) + E_m \tag{16}$$

Table 1: Mechanical properties of AA8090 matrix and AlN nanoparticles

Property	AA8090	AlN
Density, g/cc	2.68	3.26
Elastic modulus, GPa	70.3	330
Ultimate tensile strength, MPa	310	270
Poisson's ratio	0.33	0.24

3. MATERIALS METHODS

The matrix material was AA8090 aluminum alloy. AA8090 contains Si (12.50%), Cr ($\leq 0.10\%$), Cu (1.20%), Fe ($\leq 1.00\%$), Mg (1.10%), Ni (1.00%) and Zn ($\leq 0.25\%$) as its major alloying elements. The reinforcement material was

aluminum nitride (AlN) nanoparticles of average size 100nm. The mechanical properties of materials used in the present work are given in table 1.

The representative volume element (RVE or the unit cell) is the smallest volume over which a measurement can be made that will yield a value representative of the whole. In this research, a cubical RVE was implemented to analyze the tensile behavior AA8090/AlN nanocomposites (figure 6). The determination of the RVE's dimensional conditions requires the establishment of a volumetric fraction of spherical nanoparticles in the composite. Hence, the weight fractions of the particles were converted to volume fractions. The volume fraction of a particle in the RVE ($V_{p,rve}$) is determined using Eq.(21):

$$V_{p,rve} = \frac{\text{Volume of nanoparticle}}{\text{Volume of RVE}} = \frac{16}{3} \times \left(\frac{r}{a}\right)^3 \quad (21)$$

where, r represents the particle radius and a indicates the diameter of the cylindrical RVE. The volume fraction of the particles in the composite (V_p) is obtained using equation

$$V_p = (w_p/\rho_p)/(w_p/\rho_p + w_m/\rho_m) \quad (22)$$

where ρ_m and ρ_p denote the matrix and particle densities, and w_m and w_p indicate the matrix and particle weight fractions, respectively.

The RVE dimension (a) was determined by equalizing Eqs. (21) and (22). Two RVE schemes namely: without interphase (adhesion) and with interphase were applied between the matrix and the filler. The loading on the RVE was defined as symmetric displacement, which provided equal displacements at both ends of the RVE. To obtain the nanocomposite modulus and yield strength, the force reaction was defined against displacement. The large strain PLANE183 element [12] was used in the matrix and the interphase regions in all the models (table 2). In order to model the adhesion between the interphase and the particle, a COMBIN14 spring-damper element was used. The stiffness of this element was taken as unity for perfect adhesion which could determine the interfacial strength for the interface region.

To converge an exact nonlinear solution, it is also important to set the strain rates of the FEM models based on the experimental tensile tests' setups. Hence, FEM models of different RVEs with various particle contents should have comparable error values. In this respect, the ratio of the tensile test speed to the gauge length of the specimens should be equal to the corresponding ratio in the RVE displacement model. Therefore, the rate of displacement in the RVEs was set to be 0.1 (1/min).

4. RESULT AND DISCUSSION

The AlN/AA8090 nanocomposites with or without interphase were modeled using finite element analysis (ANSYS) to analyze the tensile behavior and fracture.

4.1 Tensile Behavior

An increase of AlN content in the matrix could increase the tensile strength of the nanocomposite (figure 3) having interphase around AlN nanoparticles. The maximum difference between the FEA results without interphase and the experimental results was 24.34 MPa. This differentiation can be attributed to lack of bonding between the AlN nanoparticle and the AA8090 matrix. The maximum difference between the FEA results with interphase and the experiments results was 25.37 MPa. This discrepancy can be endorsed to the presence of voids in the nanocomposites. Author's model includes the effect of voids present in the nanocomposite.

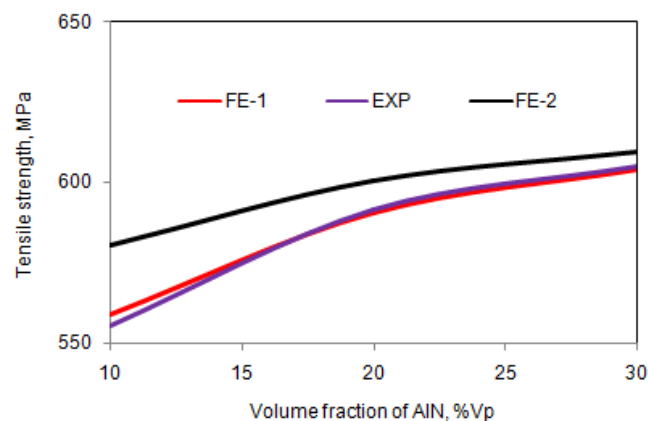


Figure 3: Effect of volume fraction on tensile strength along tensile load direction.

For 10%, 20% and 30% V_p of AlN in AA8090, without interphase and barely consideration of adhesive bonding between the AlN nanoparticle and the AA8090 matrix, the loads transferred from the AlN nanoparticle to the AA8090 matrix were, respectively, 88.83 MPa, 139.38 MPa and 144.19 MPa (figure 4) along the tensile load direction. Similarly, for 10%, 20% and 30% V_p of AlN in AA8090, with interphase and wetting between the ALN nanoparticle and the AA8090 matrix, the loads transferred from the AlN nanoparticle to the AA8090 matrix were, respectively, 132.79 MPa, 182.15 MPa and 146.72 MPa (figure 4) along the tensile load direction. Zhengang et al [13] carried a study improving wettability by adding Mg as the wetting agent. They suggested that the wettability between molten Al-Mg matrix and SiC particles is improved and the surface tension of molten Al-Mg alloy with SiC particle is reduced, and results in homogeneous particles distribution and high interfacial bond strength. For instance, addition of Mg to composite matrix lead to the formation of MgO and MgAl₂O₃ at the interface and this enhances the wettability and the strength of the composite[14]. By increasing the volume fraction of AlN the longitudinal tensile elastic modulus decreased appreciably (table 2) without interphase around AlN nanoparticles. The transverse moduli were nearly equal to the results obtained by the Rule of Mixture

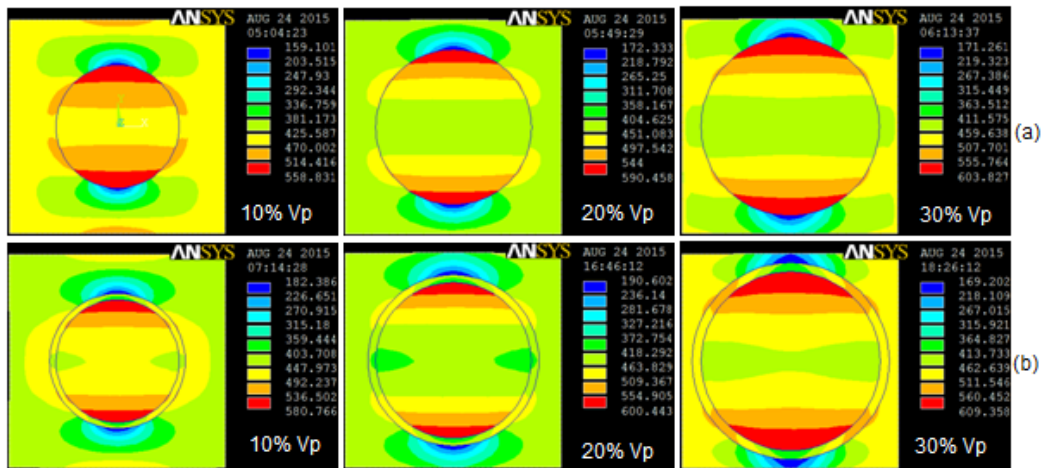


Figure 4: Tensile stresses (a) without interphase and (b) with interphase normal to load direction.

. Table 2: Elastic moduli of AA8090/AlN nano composite.

Source	Criteria	Longitudinal Elastic Modulus, GPa			Transverse Elastic Modulus, GPa		
		V _p = 10%	V _p = 20%	V _p = 30%	V _p = 10%	V _p = 20%	V _p = 30%
FEA	without interphase	1.36	1.33	1.28	1.36	1.33	1.28
FEA	with interphase	1.33	1.42	1.33	1.42	1.42	1.33
Rule of Mixture		1.42	1.79	2.17	1.13	1.24	1.36

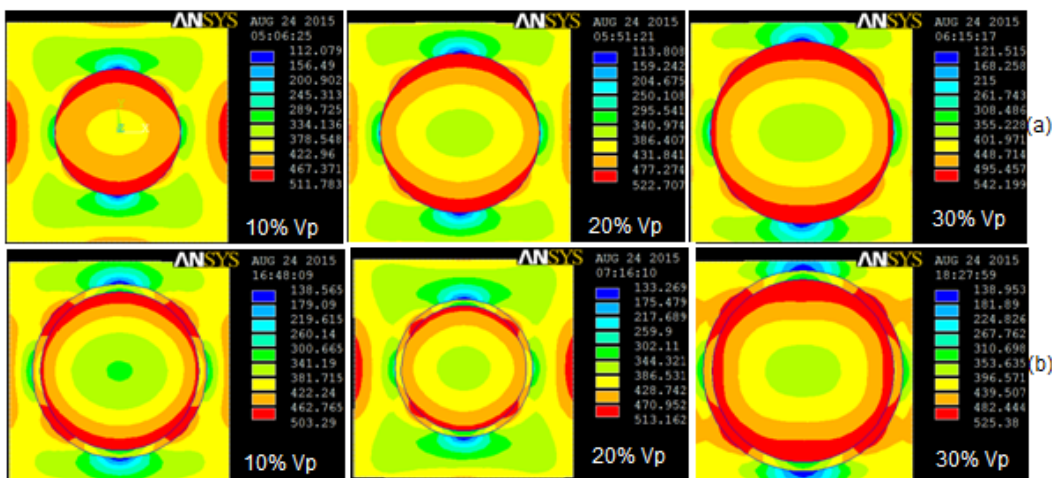


Figure 7: von Mises stress.

4.2 Fracture

Figure 5 depicts the increase of von Mises stress with increase of volume fraction of AlN. In the case of nanocomposites with interphase between the nanoparticle and the matrix, the stress was transferred through shear from the matrix to the particles resulting low stress in the matrix. The stress transfer from the matrix to the nanoparticle was less for the nanocomposites without interphase resulting high stress in the matrix. Landis and McMeeking [15] assume that the fibers carry the entire axial load, and the matrix material only transmits shear between the fibers. Based on these assumptions alone, it is generally accepted that these methods will be most accurate when the fiber volume fraction V_f and the fiber-to matrix moduli ratio E_f/E_m are high. In the present case the elastic moduli of AlN nano particle and AA8090 matrix are, respectively, 77.0 GPa and 330 GPa.

5. CONCLUSION

Without interphase and barely consideration of adhesive bonding, the tensile strength has been found to be 580.77 MPa for the nanocomposites consisting of 30%AlN nanoparticles. Due to interphase between the nanoparticle and the matrix, the tensile strength increases to 609.36 MPa. The tensile strengths obtained by author's model (with voids) are in good agreement with the experimental results. In the case of nanocomposites with interphase between the nanoparticle and the matrix, the stress is transferred through shear from the matrix to the particles. The transverse moduli of AlN/AA8090 nanocomposites have been found to be 88.26 GPa and 91.87 GPa, respectively, without and with interphase.

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